clear that if $\triangle \mathrm{XYZ}$ were to be given the rank of $\mathrm{rt} . \angle \mathrm{A}^{\prime \prime} \mathrm{B}^{\prime \prime} \mathrm{C}^{\prime \prime}$ and a new one were to be formed from it, as it is formed from $\angle \mathrm{A}^{\prime \prime} \mathrm{B}^{\prime \prime} \mathrm{C}^{\prime \prime}$, then the point $\mathrm{S}^{\prime \prime}$ would fall upon $H$. Therefore, since $H$ is the in-center of $\triangle H_{a} H_{b} H_{c}, S^{\prime \prime}$ must be the in-center of $\triangle \mathbf{M}_{a^{\prime \prime}} \mathbf{M}_{b^{\prime \prime}} \mathbf{M}_{c^{\prime \prime}}$.

Therefore we see that the six Simson's lines, three with reference to one $\triangle$ and three with reference to the other, meet in the same point.
32. This, at the same time, establishes another even more interesting proposition, namely : If the Simson's lines of the vertices of a first _ with reference to a second $\triangle$ concur in a point $S^{\prime \prime}$, then the Simson's lines of the vertices of the second $\triangle$ with reference to the first $\triangle$ concur in the same point $S^{\prime \prime}$.

The broad scope covered by this proposition would enable me to double in number the points of concurrency of Simson's lines, but there would be little benefit in merely pointing them out, as the interested reader can easily see them for himself.

A Bibliography of Foundations of Geometry. By Morton Clark Bradley.

Euclid's treatment of parallels and angles and his definitions and axioms-particularly his twelfth-are the points of controversy that cause the most discussion. For nearly twenty centuries Euclid's work remained unquestioned. Since John Kepler's day, howerer, there hare been new theories constantly adranced, theories built on axioms and definitions, a part of which, at least, are different from those of Euclid. The most important of the non-Euclideans are John Bolyai, Lobatschevski, Helmholtz, Riemann, Clifford, Henrici, Caley, Sylvester and Ball. The most prominent exponent of the non-Euclidean ideas in this country is Prof. Geo. Bruce Halsted, of Texas University. These mathematicians hold that Euclid's twelfth axiom is not, strictly speaking, an axiom-that it is not "a self-evident and necessary truth," but that it requires demonstration. They claim, too, that his definitions are not sufficient nor necessarily intelligible. Some of these men hare built up new theories upon their substituted axioms and definitions, retaining those of Euclid that fit their theories. A few of these "reform" works are mere quibbles on words, but others deserve the serious consideration of all interested in pure geometry.

The list following is a complete list of English references to be found in the mathematical library of the University of Indiana or in the private-
library of Dr. Aley. Chrystal says the bibliography credited to Mr. Halsted contains all the references up to its time, save one, giving the nonEuclidean arguments. The list is not complete in arguments for Euclid, it being impossible to enumerate all the editions of Euclid, edited and upheld by the different mathematicians. The list is complete enough, however, to assure the reader that there are arguments for Euclid as well as against lim.

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## Point-Invariants for the Lie Groups of the Plane.

By David A. Rothrock.

Among the many interesting and important applications of Lie's Theory of Transformation Groups none deserves more prominent mention than the application to invariant theory. Whether the invariants dealt with be functions or equations, surfaces and curves or points, equally interesting results are obtained. The present paper has to do with the determination of the point-invariants for the finite continuous groups of the plane as classified by Lie in Vol. XVI. of the Mathematische Annalen. In the first part of the paper is sketched a brief outline of the Lie theory leading up to the point-invariant, then follow the calculations of the invariant functions.

An infinitesimal point-transformation gives to $x$ and $y$ the increments

$$
\delta \mathrm{x}=\xi(\mathrm{x}, \mathrm{y}) \delta \mathrm{t}, \delta \mathrm{y}=\eta(\mathrm{x}, \mathrm{y}) \delta \mathrm{t},
$$

